

Corrections to J.Ackermann et al., Robust Control, Springer, London, 2002

Page	Where	Correct	Instead of
25	Caption 1.9	two degree	twodegree
32	Example 2.3 (also later examples in chapter 2)	Example 2.1	Example 2.3
40	Eq. 2.4.1	$d_0 + d_1s + s^2$	$d_0 + d_1s + d_2s^2$
40	Eq. 2.4.3	$\hat{\mathbf{h}}^T$	$\hat{\mathbf{h}}$
41	Eq. 2.4.7	$\hat{\mathbf{h}}^T$	$\hat{\mathbf{h}}$
47	line 7	$-6.4 + 4\omega^2$	$-1.6 + \omega^2$
52	line 12	$p_n = b_7$	$p_n = b_6$
	line 18	0.1	0.01
54	line 3	one real ω_k	no real ω_k
58	line 11	(2.7.3)	(2.7.4)
86	line 3	$(b/a)^2 - b^2$	$(b/a)^2 b^2$
	line 4	$(b/a)^2 + b^2$	$(b/a)^2 - b^2$
94	line 14	$I_A\sigma + R_A\omega$	$I_A\sigma - R_A\omega$
	lines 21 to 23	-	+
	last line	$-c/a + (b/a)^2$	$c/a - (b/a)^2$
95	1st line	same under root sign	
103	Eq. 4.5.16 (right hand side)	q_2	q_1
	Eq. 4.5.16 (right hand side)	exchange both determinants	
107	line 2	section 5.2	this section
113	Eq. 5.1.10	$-G(s)y(s)$	$-G(s), y(s)$
120	Figure 5.22	$z_3, \partial\Theta_3, z_{2,3}, \partial\Theta_2, z_{1,2}, \partial\Theta_1$	$z3, dTheta3, z23, dTheta2, z12, dTheta1$
130	Figure 5.29	1.8 0.8	0.8 1.8
187	Eq. 6.3.22	$r = 0\beta$	$r = -0\beta$
190	Remark 6.7	belongs on top of next page	
196	after 6.4.8	$\tilde{\mu} \in [\mu^- m^- / m^+; 1]$	m
	line 7 from below	m^+	m
197	line 3	$\tilde{\mu} \dots$	$-\tilde{\mu} \dots$

Page	Where	Correct	Instead of
208	line 10	$:\frac{n_{dec}}{s}$	$:\frac{n_{dec}}{s} :$
210	table 6.2, D	$-c_F \ell_F]$	$-c_F \ell_F)$
216	line 6 from below	D_{dec}	d_{dec}
280	1st line	$b(s^2 + \bar{b}_1 s + \bar{b}_0)$	$b(s^2 + b_1 s + b_0)$
358	line 8 from below	d_0	d_o
364	line 12	value set	values set
421	line 3 from below	close to the ideal	close, the ideal
426	Theorem 11.6, i.	$p(z, \mathbf{q}^0)$	$p(z, \mathbf{q}_0)$
427	lines 11, 9, 7 from below	Condition ii, iii, iv	2, 3, 4
434	last line	$S =$	$s =$
443	Figure 11.11	omit three black bars	
	Caption 11.11	11.6	10.6